

Hamid Taheri | Computer Vision and Robotics

✉ Gmail

🌐 LinkedIn

🌐 Webpage

☎ +49 1764 5657055

🏠 Rathausstr. 5, 74080 Heilbronn, Germany

Professional Experience

- 2026 Mar – Present **Applied AI Software Engineer, amitego Engineering GmbH, Germany.** Developing VMask, an AI-powered privacy masking system for remote desktop sessions. Working on real-time OCR, computer vision, GPU inference, backend services, and Linux-based remote desktop infrastructure.
- 2025 Nov – 2026 Feb **AI/ML and Full-Stack Innovation Intern, PreZero Stiftung & Co. KG, Germany.** Worked on two AI logistics projects: route optimization and predictive container pickup planning. Built ML models, backend logic, and a full-stack prototype for internal testing.
- 2024 Sep – 2025 Mar **Computer Vision Engineer – Intern, Schwarz IT KG, Germany.** Developed object detection, anomaly detection, and OCR models for industrial applications. Worked with **Python, Docker, Azure, Kubernetes, and CI/CD.**
- 2017 Sep – 2018 Feb **Instrumentation Engineer, South Isfahan Power Station, Iran.** Worked on calibration, monitoring, sensor integration, and control loop tuning for instrumentation systems.

Education

- 2023 Mar – present **Software Developer, 42 Heilbronn, Germany.** Developed proficiency in **Python, C, C++, Shell scripting, and Docker** through intensive, project-based training in systems programming and AI integration.
- 2019 – 2022 **M.Sc. Electrical Engineering, Control Systems.** K. N. Toosi University of Technology, Tehran, Iran.
Thesis title: *Continuous Control of Nonholonomic Mobile Robot Navigation Deep Reinforcement Learning (PPO, DDPG)*. Focused on real-time, vision-based autonomous navigation and deep control strategies for mobile robotics.
- 2014 – 2018 **B.Sc. Electrical Engineering, Control Systems.** Isfahan University, Isfahan, Iran.
Thesis title: *Mentor Robot Position Control Using Forward Kinematic Concept and Mobile Sensors Data*. Developed control algorithms integrating sensor data and kinematic modeling for mobile robot positioning.

Research Publications

Journal Articles

- 1 **Hamid Taheri, S. R. Hosseini, and M. A. Nekoei, “Deep Reinforcement Learning with Enhanced PPO for Safe Mobile Robot Navigation”, *arXiv preprint*, vol. 2405.16266, 2024.** [URL: https://arxiv.org/abs/2405.16266](https://arxiv.org/abs/2405.16266).
- 2 **S. R. Hosseini, Hamid Taheri, and M. Teshnehlab, “ENet-21: An Optimized Light CNN Structure for Lane Detection”, *arXiv preprint*, vol. 2403.19782, 2024.** [URL: https://arxiv.org/abs/2403.19782](https://arxiv.org/abs/2403.19782).

Skills

Languages	📖	Fluent in English, intermediate in German (B1), and native in Persian.
Coding	📖	C/C++, Python, MATLAB, Shell.
DevOps Tools	📖	Docker, Kubernetes, Git, ROS, Azure Pipelines.
Web Dev	📖	HTML, CSS, JavaScript.
AI Frameworks	📖	PyTorch, TensorFlow, Scikit-learn, OpenCV, LangChain, Hugging Face.

Miscellaneous Experience

Projects

- 2025 📖 **3D classification and segmentation.** Implementation of 3D deep learning architectures including PointNet, PointNet++, PointMLP, and DGCNN for classification and segmentation. [\[GitHub\]](#)
- 📖 **3D Object Detection on RGB-D Data.** Built an end-to-end 3D object detection pipeline using RGB-D data with a custom architecture, handling training on a small dataset. [\[GitHub\]](#)
- 2024 📖 **Safe Mobile Robot Navigation using PPO and SAC.** Built a deep RL-based navigation system (PPO, DDPG) with ROS and LiDAR, focusing on collision avoidance in dynamic environments. [\[GitHub\]](#)
- 📖 **Object Detection with YOLOv3.** Built a real-time object detection pipeline with YOLOv3 and non-max suppression on COCO dataset, achieving 90% mAP. [\[GitHub\]](#)
- 📖 **ViT-AnomalyDetection.** Designed a hybrid Vision Transformer and CNN model for industrial anomaly detection on the MVTec dataset. [\[GitHub\]](#)
- 📖 **Webserv.** Developed a complete HTTP server in modern C++ to fully understand the HTTP protocol and non-blocking network programming. [\[GitHub\]](#)
- 📖 **C++ Modules.** Implemented a complete C++ module to deepen my understanding through practical, meaningful projects. [\[GitHub\]](#)
- 📖 **MiniRT.** Built a ray tracer in C for photorealistic rendering with lighting, shadows, and material reflections. [\[GitHub\]](#)
- 2023 📖 **MiniShell.** C-based Unix shell emulator featuring command parsing, piping, and redirection. [\[GitHub\]](#)
- 📖 **Custom MLP Library.** Developed a minimal neural network framework with numpy, supporting classification/regression with emphasis on learning efficiency. [\[GitHub\]](#)
- 2021 📖 **Fault Detection in Rotating Machinery.** Achieved 99% accuracy and 98% F1-score using Deep Stack Autoencoders for predictive maintenance. [\[GitHub\]](#)

Awards and Achievements

- 2025 📖 **Top Performer, Audi - XL2 DeepRacer RL Competition,** Germany. Ranked among the top participants in virtual and on-site reinforcement learning competition for autonomous navigation.
- 2019 📖 **Ranked 67th, National Master's Entrance Exam,** Iran. Among top 0.2% out of 30K+ participants.
- 2018 📖 **Exceptionally Talented Student.** Admitted to Iran University of Science and Technology without an entrance exam.
- 📖 **Top 3 Graduate in B.Sc. Program.** University of Isfahan.

Certifications

- 2024 📖 **Generative AI with Large Language Models.** [\[Coursera\]](#)
- 2023 📖 **Sequence Models.** [\[Coursera\]](#)
- 📖 **Supervised Machine Learning: Regression and Classification.** [\[Coursera\]](#)
- 📖 **Natural Language Processing with TensorFlow.** [\[Coursera\]](#)
- 2022 📖 **Convolutional Neural Networks.** [\[Coursera\]](#)